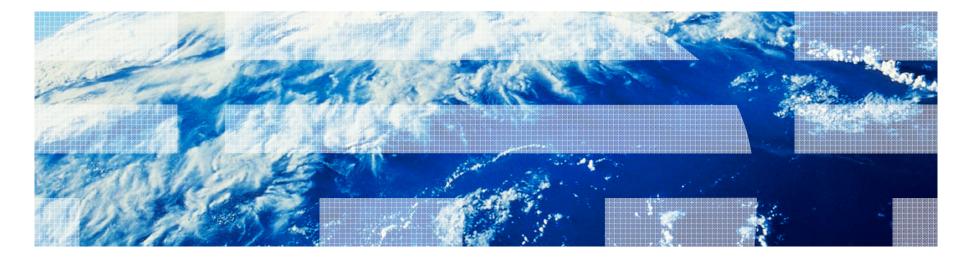


# Scalable and Numerically Stable Descriptive Statistics in SystemML

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### **SystemML**

- Pervasive need to enable machine learning (ML) on massive datasets
- Increasing interest in implementing a ML algorithms on MapReduce
- Directly implementing ML algorithms on MapReduce is challenging
- Solution: SystemML A Declarative Approach to Machine Learning on MapReduce



### SystemML Overview

# High-level language with ML specific constructs

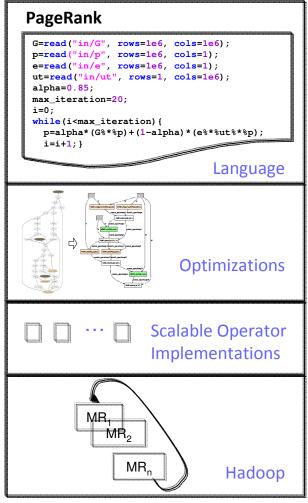
- Syntax is similar to R and Matlab
  - Matrix, vector and scalar data types
  - Linear algebra and mathematics operators

### Optimizations based on data and

- system characteristics
  - Cost-based and rule-based optimization
  - Job generation heuristics

#### □ Scalable implementations on Hadoop

- Handle large sparse data sets
- Parallelization is *transparent* to end users



**ICDE 2011** 



### **Example ML Algorithms Supported in SystemML**

- □ Classification: linear SVMs, logistic regression
- □ Regression: linear regression
- □ Matrix Factorization: NMF, SVD, PCA
- □ Clustering: k-means
- □ Ranking: PageRank, HITS
- - Univariate Statistics:
    - Scale: Sum, Mean, Harmonic mean, Geometric mean, Min, Max, Range, Median, Quantile, Interquartile-mean, Variance, Standard deviation, Coefficient of variance, Central moment, Skewness, Kurtosis, Standard error of mean, Standard error of skewness, Standard error of kurtosis
    - Categorical: Mode, Per-category frequencies
  - Bivariate Statistics:
    - Scale-scale: Covariance, Pearson correlation
    - Scale-categorical: Eta, ANOVA F measure
    - Categorical-categorical: Chi-square coefficient, Cramer's V, Spearman correlation



### How hard is it?

Seemingly trivial to implement in MapReduce

• Most descriptive statistics can be written in certain summation form

Sum	$s = \sum x_i$
Mean	$\bar{x} = \frac{1}{n} \sum x_i$
Variance	$s^{2} = \frac{1}{n-1} \sum_{i=1}^{n-1} (x_{i} - \bar{x})^{2}$ $= \frac{1}{n-1} \sum_{i=1}^{n-1} x_{i}^{2} - \frac{1}{n(n-1)} (\sum_{i=1}^{n-1} x_{i})^{2}$

- Pitfall: these straight forward implementations can lead to disasters in *numerical accuracy*
- □ Problem gets **worse** with increasing volumes of data



### **Background: Floating Point Numbers**

- Source of Inaccuracy: finite precision arithmetic for floating point numbers
- □ Floating point number system  $F \subseteq \mathbb{R}$ :  $y = \pm \beta^e \times .d_1 d_2 \dots d_t$  ( $0 \le d_i \le \beta 1$ )
  - base в,
  - precision t,
  - exponent range  $e_{\min} \le e \le e_{\max}$
  - IEEE double: *β=2, t=53, e*<sub>min</sub> *=-1021, e*<sub>max</sub> *=1024*
- □ Floating point numbers are **not** equally spaced.
  - Example number system:  $\theta = 2$ , t = 3,  $e_{\min} = -1$ , and  $e_{\max} = 3$

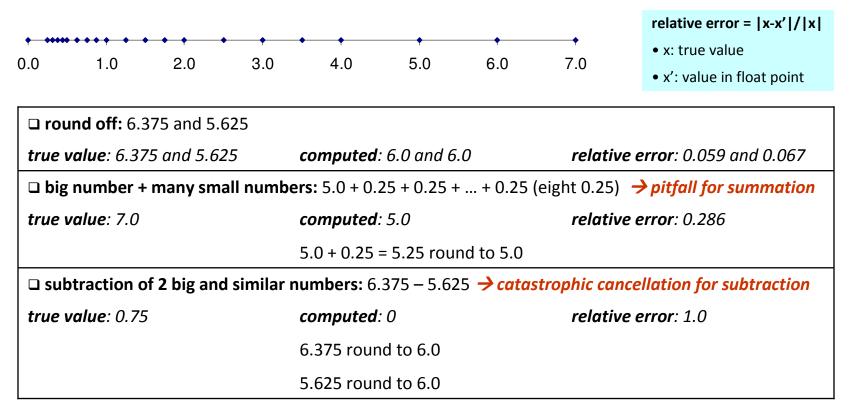
F={ 0, ±0.25, ±0.3125, ±0.375, ±0.4375, ±0.5, ±0.625, ±0.75, ±0.875, ±1.0, ±1.25, ±1.5, ±1.75, ±2.0, ±2.5, ±3.0, ±3.5, ±4.0, ±5.0, ±6.0, ±7.0 }



### **Background: Numerical Accuracy**

□ Example number system:  $\theta = 2$ , t = 3,  $e_{\min} = -1$ , and  $e_{\max} = 3$ 

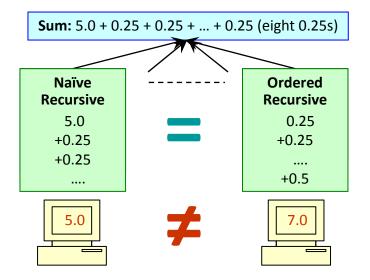
F={0, ±0.25, ±0.3125, ±0.375, ±0.4375, ±0.5, ±0.625, ±0.75, ±0.875, ±1.0, ±1.25, ±1.5, ±1.75, ±2.0, ±2.5, ±3.0, ±3.5, ±4.0, ±5.0, ±6.0, ±7.0 }





### **Background: Numerical Stability**

- Algebraically equivalent algorithms for the same calculation produce different results on digital computers
  - Some damp out errors
  - Some magnify errors



- Numerical stability is a desirable property of numerical algorithms
  - Algorithms that can be proven not to magnify approximation errors are called *numerically stable*



### **Importance of Numerical Stability**

- Numerical stability issue has been largely ignored in big data processing
  - e.g. PIG and HIVE, are using well-known unstable algorithms for computing some basic statistics

□ How about software floating point packages, e.g. BigDecimal?

- Arbitrary precision, but very slow
  - +, -, \*: 2 orders of magnitude slower
  - /: 5 orders of magnitude slower

□ Goal of this Talk: share our experience on descriptive

statistics algorithms for big data

- Scalable database people already understand
- Numerically Stable need more attention !!!!!



## **Numerically Stable Summation**

- □ Naïve Recursive: unstable
- □ Sorted Recursive: better for nonnegative but needs an expensive sort
- □ Kahan: efficient and stable [Kahan 1965]
  - Recursive summation with a correction term to compensate rounding error
    - (s', c') = *KahanAdd* (s, c , a)

s/s': old/new sum
c/c': old/new correct
a: number to add

sum correct add	a'= a + c s'= s + a' c' = a'- (s'- s)	<b>Stability Property:</b> relative error bound independent of problem size n, when n is less than O(10 <sup>16</sup> ) for IEEE doubles	Kahan -
MR	Kahan in Syste	emML:	+

- Mapper: apply Kahan to compute partial sum and correction
- Reducer: apply Kahan on partial results to compute sum

 $(s, c) = KahanAdd (s_1, c_1 + c_2, s_2)$ 

s<sub>1</sub>/s<sub>2</sub>: partial sums c<sub>1</sub>/c<sub>2</sub>: partial corrects s: total sum

c: total correct

**Our Proof**: relative error bound independent of problem size n, as long as each mapper processes less than  $O(10^{16})$  numbers

-	sum	correction	
	5.0	0	
+	0.25		
-	5.0	0.25	
+	0.25		
_	6.0	-0.5	
+	0.25		
-	6.0	-0.25	
+	0.25		
-	6.0	0	

#### <sup>10</sup> MR Kahan scales to larger problem size with numerical accuracy.

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# **Numerically Stable Mean**

### □ Naïve sum/count: unstable

### □ Incremental: stable [Chan et al 1979]

```
\label{eq:n1} \begin{array}{l} n_1, n_2: \text{ partial counts}, \mu_1, \mu_2: \text{ partial means} \\ n = n_1 + n_2 \\ \delta = \mu_2 - \mu_1 \\ \mu = \mu_1 + \delta n_2/n \end{array}
```

#### □ **MR Incremental**: adapt Incremental to MapReduce

$$\begin{split} &n = n_1 + n_2 \\ &\delta = \mu_2 - \mu_1 \\ &\mu = \mu_1 \stackrel{\bowtie}{\sim} \delta n_2 / n \quad (\stackrel{\bowtie}{\sim} -- KahanAdd, \text{ maintain a correction term for } \mu) \end{split}$$

### **Numerically Stable Higher-Order Statistics**

- □ **Higher order statistics**: central moment, variance, standard deviation, skewness, kurtosis (core: central moment  $m_p = \frac{1}{n} \sum_{i=1}^{n} (x_i \bar{x})^p$ )
- **2-Pass**: 1<sup>st</sup> pass to compute mean, 2<sup>nd</sup> pass to compute m<sub>p</sub>
  Stable, but needs 2 scans of data
- **Textbook 1-Pass:** textbook rewrites  $m_2 = \frac{1}{n} \sum_{i=1}^n (x_i \bar{x})^2 = \frac{1}{n} \sum_{i=1}^n x_i^2 \frac{1}{n^2} (\sum_{i=1}^n x_i)^2$ 
  - Notoriously unstable (due to catastrophic cancellation), can even produce negative result for m<sub>p</sub> when p%2=0
  - Unfortunately, widely used in practice
- □ Incremental: stable\* & 1 pass [Bennett et al 2009]

$$n = n_a + n_b, \delta = \mu_b - \mu_a, \mu = \mu_a \boxtimes n_b \frac{\delta}{n}$$
$$M_p = M_{p,a} \boxtimes M_{p,b} \boxtimes \{\sum_{j=1}^{p-2} \binom{p}{j} [(-\frac{n_b}{n})^j M_{p-j,a} + (\frac{n_a}{n})^j M_{p-j,b}] \delta^j + (\frac{n_a n_b}{n} \delta)^p [\frac{1}{n_b^{p-1}} - (\frac{-1}{n_a})^{p-1}] \}$$

- □ MR Incremental: adapt Incremental to MapReduce
  - Use KahanAdd



### **Numerically Stable Covariance**

- **2-Pass**: 1<sup>st</sup> pass to compute means, 2<sup>nd</sup> pass to compute covariance
  - Stable, but needs 2 scans of data
- **Textbook 1-Pass:** textbook rewrites  $c_2 = \frac{1}{n-1} \sum_{i=1}^n (x_i \bar{x})(y_i \bar{y}) = \frac{1}{n-1} \sum_{i=1}^n x_i y_i \frac{1}{n(n-1)} (\sum_{i=1}^n x_i)(\sum_{i=1}^n y_i)$ 
  - Notoriously unstable (catastrophic cancellation)
  - Unfortunately, widely used in practice
- □ Incremental: practically stable & 1 pass [Bennett et al 2009]

$$n = n_a + n_b, \ \delta_x = \mu_{x,b} - \mu_{x,a}, \ \mu_x = \mu_{x,a} \ \mathbf{\Xi} \ n_b \frac{\delta_x}{n}, \ \delta_y = \mu_{y,b} - \mu_{y,a}, \ \mu_y = \mu_{y,a} \ \mathbf{\Xi} \ n_b \frac{\delta_y}{n}$$
$$C = C_a \ \mathbf{\Xi} \ C_b \ \mathbf{\Xi} \ \frac{n_a n_b}{n} \delta_x \delta_y$$

- □ **MR Incremental**: adapt Incremental to MapReduce
  - Use KahanAdd



## **Experiment Results**

Example Univariate Statistics			Ranges : R1= [1.0 – 1.5), R2= [1000.0 – 1000.5), R3= [1000000.0 – 100						
	Size (million)	Su	m	Mean		Variance		Standard Deviation	
Range		SML	Naïve	SML	Naïve	SML	Textbook	SML	Textbook
	10	16.8	14.4	16.5	14.4	15.4	5.9	15.9	6.2
R2	100	16.1	13.4	16.9	13.4	15.6	5.3	15.8	5.6
	1000	16.6	13.1	16.4	13.1	16.2	4.9	16.4	5.2
	10	15.9	14.0	16.3	14.0	14.4	0	14.7	0
R3	100	16.0	13.1	16.9	13.1	12.9	Negative	13.2	NA
	1000	16.3	12.9	16.5	12.9	13.2	Negative	13.5	NA

#### **Example Bivariate Statistics**

	Size (million)	CoVa	riance	Pearson-R		
Range		SML	Textbook	SML	Textbook	
	10	15.0	8.4	15.1	6.2	
R1 vs R2	100	15.6	8.5	15.4	6.4	
	1000	16.0	8.7	15.7	6.2	
	10	13.5	3.0	13.5	3.0	
R2 vs R3	100	12.8	2.8	12.7	NA	
	1000	13.6	3.9	13.8	NA	

#### Significantly better accuracy! No sacrifice to performance!

- Data Sets: uniform distribution in 3 ranges
  - R1= [1.0−1.5), R2= [1000.0−1000.5), R3 = [1000000.0 - 1000000.5)
  - modeled after NIST StRD benchmark

#### Accuracy Measure:

- *LRE* = *log*(relative error)
- # significant digits that match between the computed value and the true value.
- true value: produced by BigDecimal with precision 1000.

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# Lessons Learned (1/2)

- Many existing numerical stable techniques can be adapted to the distributed environment
- Divide-and-conquer design helps in scaling to larger data sets while achieving good numerical accuracy
  - e.g. MR Kahan can handle more data than Kahan with numerical accuracy
- □ Kahan technique is useful beyond simple summation

#### **R1 10 million points**

Vari	ance	Std			
×	+	×	+		
16.0	13.5	15.9	13.8		

#### R1 vs R2 10 million points

Cova	riance	Pearson-R			
×	+	×	+		
15.0	14.2	15.1	13.0		



# Lessons Learned (2/2)

### □ Shifting can be used for improved accuracy

- Accuracy degrades as magnitude of values increases
- Achieve better accuracy by shifting the data points by a constant prior to computation

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				יאי		10

	Sum		Mean		Variance		Standard Deviation	
Range	SML	Naïve	SML	Naïve	SML	Textbook	SML	Textbook
1000 - 1000.5	16.8	14.4	16.5	14.4	15.4	5.9	15.9	6.2
1000,000 - 1000,000.5	15.9	14.0	16.3	14.0	14.4	0	14.7	0

□ Performance need not be sacrificed for accuracy



#### □ Recommended Reading:

• Nicholas J. Higham. *Accuracy and Stability of Numerical Algorithms*. SIAM, 2nd edition, 2002.

### □ Thanks! and Questions?